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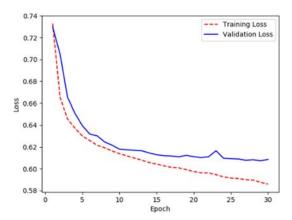


Fig 1. DeepAutoEnCF-U Training Vs. Validation Loss for MovieLens-1M dataset (80/10/10 split) Without Features

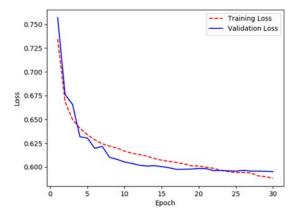


Fig 2. DeepAutoEnCF-U Training Vs. Validation Loss for MovieLens-1M dataset (80/10/10 split) with Age and Gender Features

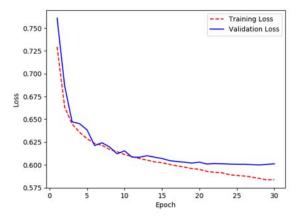


Fig 3. DeepAutoEnCF-U Training Vs. Validation Loss for MovieLens-1M dataset (80/10/10 split) with Age, Gender and Movie Genre Weightage Features

Fig. 4 shows performance of DeepAutoEnCF-U on MovieLens-1M dataset for 60/20/20 split with features. The model overfits for this split with features. It shows similar performance with and without features for this split.

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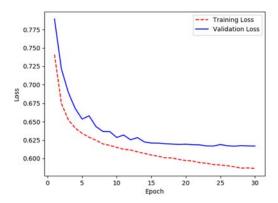


Fig 4. DeepAutoEnCF-U Training Vs. Validation Loss for MovieLens-1M dataset (60/20/20 split) with Age, Gender and Movie Genre Weightage Features

Fig. 5 shows the training loss against the validation loss of DeepAutoEnCF-I for MovieLens-1M dataset without any features. Fig. 6 shows the training loss against the validation loss of DeepAutoEnCF-I on MovieLens-1M dataset with movie genre feature. Here also the model performs better with features which can perform better when the model is generalized.

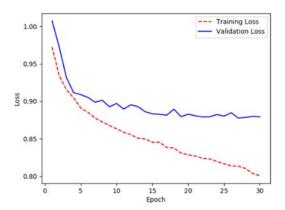


Fig 5. DeepAutoEnCF-I Training Vs. Validation Loss for MovieLens-1M dataset (80/10/10 split) without Features

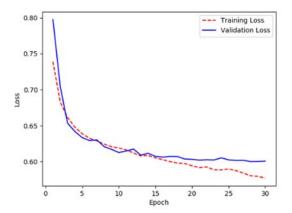


Fig 6. DeepAutoEnCF-I Training Vs. Validation Loss for MovieLens-1M Dataset (80/10/10 split) with Movie Genre Feature

Fig. 7 shows performance of DeepAutoEnCF-I for MovieLen-1M dataset for 60/20/20 dataset split. For item based approach also the model shows either overfit or unpresentable performance. For both the approaches the performance (RMSE) and the learning improves when features are added to the input with 90/10/10 dataset split.

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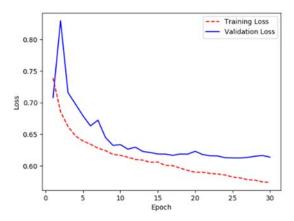


Fig 7. DeepAutoEnCF-I Training Vs. Validation Loss for MovieLens-1M Dataset (60/20/20 split) with Movie Genre Feature

7. Conclusions

For both the datasets, the proposed system outperforms the traditional collaborative filtering algorithms. For MovieLens 100K dataset DeepAutoEnCF-I showed better performance than DeepAutoEnCF-U. For MovieLens-1M dataset both the approaches, user based and item based, show improvement in performance when features are added to the input. The performance of DeepAutoEnCF-I improved more than DeepAutoEnCF-U as compared to their performance without features. Whenever the data is spare, adding new features supports the learning process and improves the performance. Denoising Autoencoders with dropout improve the performance of recommender systems for predicting ratings. New features can be thought and added to the input further for improving the performance of recommender systems with deep learning through denoising autoencoders.

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